



## **Modeling and Control of Robot Manipulators**

Lorenzo Sciavicco

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#### Modeling and Control of Robot Manipulators Lorenzo Sciavicco

This text, aimed at senior undergraduate/graduate courses in robotics, provides a guide to the foundations of robotics: modelling, mechanics and control. Fundamental aspects covered include kinematics, statics and dynamics of manipulators, and trajectory planning and motion control in free space.



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